A Framework for Manipulating and Searching Multiple Retrieval Types

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ABSTRACT

Conventional retrieval systems view documents as a unit and look at different retrieval types within a document. We introduce Proteus, a framework for seamlessly navigating books as dynamic collections which are defined on the fly. Proteus allows us to search various retrieval types. Navigable types include pages, books, named persons, locations, and pictures in a collection of books taken from the Internet Archive. The demonstration shows the value of multi-type browsing in dynamic collections to peruse new data.

Categories and Subject Descriptors

H.3.3 [Information Storage and Retrieval]: Information Search and Retrieval—Search Process; H.5.4 [Information Storage and Retrieval]: Hypertext/Hypermedia—Navigation

General Terms

Design, Human Factors, Standardization

Keywords

Proteus, object search, navigation

We introduce Proteus, a data model for representing, searching, and browsing objects extracted from book collections. The Proteus model defines an API for potential data sources to implement and use to provide and exchange information using that data model. Implementing this API allows Proteus to use the items from the system as part of the retrievable set of items, enabling horizontal movement between the “vertical” data types.

We demonstrate the value of Proteus with an implementation of the framework we have developed at the Center for Intelligent Information Retrieval. We have indexed a set of books from the Internet Archive. We use focused collections centered on topics such as William Shakespeare, the westward migration of American settlers, and the American Revolution. In each instance we provide the ability to retrieve pages, books, named persons, locations, and images from these collections, and navigate between them. We also integrate information from DBPedia to provide an existing ontology for the identified objects in the books.

We see the demonstration as an opportunity for users to browse a collection in a new way and discover information that would otherwise be difficult or impossible to deduce through previous navigation systems. The demonstration will be available at http://books.cs.umass.edu website.

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REFERENCES
